

# FMSoft

## Lecture 5 — Model checking for CTL

(lecture version)

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- Why both smallest and greatest fixpoints are going to be important for us?
- Recall our goal: computing

$$[[\phi]]^{\mathcal{M}} := \{s \in \mathcal{M} \mid s \models \phi\}$$

- There are some obvious functions  $2^S \rightarrow 2^S$
- Consider  $(\text{EX})A := \{s \in S \mid \exists t. s \longrightarrow t \ \& \ t \in A\}$  ...
- ...and  $(\text{AX})A := \{s \in S \mid \forall t. s \longrightarrow t \Rightarrow t \in A\}$
- ...and  $f_1(A) = [[\phi]]^{\mathcal{M}} \cap (\text{AX})A$  ...
- ...now contrast it with  $f_2(A) = [[\phi]]^{\mathcal{M}} \cup (\text{EX})A$

# Equivalences for fixpoint computation

- $AG\phi \equiv \phi \wedge AXAG\phi$
- $EG\phi \equiv \phi \wedge EXEG\phi$
- $AF\phi \equiv \phi \vee AXAF\phi$
- $EF\phi \equiv \phi \vee EXEF\phi$
- $A[\phi U \psi] \equiv \psi \vee (\phi \wedge AXA[\phi U \psi])$
- $E[\phi U \psi] \equiv \psi \vee (\phi \wedge EXE[\phi U \psi])$

## Denotations as fixpoints

- $[\text{AG}\phi]^{\mathcal{M}} = [\phi]^{\mathcal{M}} \cap (\text{AX})[\text{AG}\phi]^{\mathcal{M}}$
- $[\text{EG}\phi]^{\mathcal{M}} = [\phi]^{\mathcal{M}} \cap (\text{EX})[\text{EG}\phi]^{\mathcal{M}}$
- $[\text{AF}\phi]^{\mathcal{M}} = [\phi]^{\mathcal{M}} \cup (\text{AX})[\text{AF}\phi]^{\mathcal{M}}$
- $[\text{EF}\phi]^{\mathcal{M}} = [\phi]^{\mathcal{M}} \cup (\text{EX})[\text{EF}\phi]^{\mathcal{M}}$
- $[\text{A}[\phi\text{U}\psi]]^{\mathcal{M}} = [\psi]^{\mathcal{M}} \cup ([\phi]^{\mathcal{M}} \cap (\text{AX})[\text{A}[\phi\text{U}\psi]]^{\mathcal{M}})$
- $[\text{E}[\phi\text{U}\psi]]^{\mathcal{M}} = [\psi]^{\mathcal{M}} \cup ([\phi]^{\mathcal{M}} \cap (\text{EX})[\text{E}[\phi\text{U}\psi]]^{\mathcal{M}})$

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- ...and recall that another exercise is to verify all these equivalences hold ...

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- Assume  $A \subseteq [\phi]^M \cap (AX)A$
- Is it the case that  $A \subseteq [AG\phi]^M$ ?
- ... prove by induction that for any  $n$ , any point reachable from a given  $s \in A$  in  $n$  steps lies in  $A \cap [\phi]^M$  ...

- Note that we've now half-verified that

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- ...given any  $s \notin A$  construct inductively  $\pi \in \Pi(s)$  which does not intersect  $A$  and note it does not intersect  $[[\phi]]^{\mathcal{M}}$  either ...

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- Notice the different flavour of this proof

Least fixpoints require witnessing, greatest are safety properties

- Again, we've now half-verified that

$$[[AF\phi]]^{\mathcal{M}} = [[\phi]]^{\mathcal{M}} \cup (AX)[[AF\phi]]^{\mathcal{M}}$$

- We have shown that  $[[AF\phi]]^{\mathcal{M}}$  is below all prefixpoints of

$$f_3(A) := [[\phi]]^{\mathcal{M}} \cup (AX)A$$

- An exercise for you is to show it is a prefixpoint of  $f_3$  itself

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- ...but let us describe this “pure least fixpoints” strategy first
- We compute  $[[\phi]]^M$  passing through the model and **labelling** states with increasingly complex subformulas of  $\phi$

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- $$[[E[\psi_1 U \psi_2]]]^{\mathcal{M}} = [[\psi_2]]^{\mathcal{M}} \cup ([\psi_1]]^{\mathcal{M}} \cap (EX)[E[\psi_1 U \psi_2]]^{\mathcal{M}})$$

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- Note on complexity: a naïve implementation yields  $O(|\phi| * |S|^2 * |\longrightarrow|)$

With some care in the implementation of **AF** labelling, we should be able to get down to  $O(|\phi| * |S| * (|S| + |\longrightarrow|))$  claimed by Huth&Ryan *Logic in Computer Science* book, § 3.6 on model-checking algorithms

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- linear in the size of the formula, quadratic in the size of the model

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- ...linear **both** in the size of the formula and the size of the model!



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- how would they fare here?

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- More generally, a **fairness condition**  $C$  is any conjunction of the above three

Baier and Katoen, *Principles of Model Checking*, § 6.5

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- $\Pi_C(s)$  is the set of all  $C$ -fair paths starting at  $s$

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- Other connectives work in a similar way

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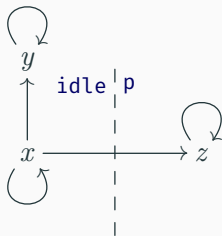


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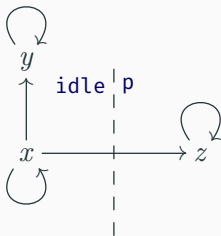
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- 



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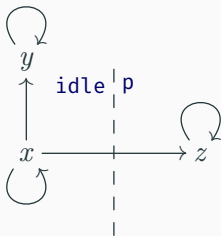
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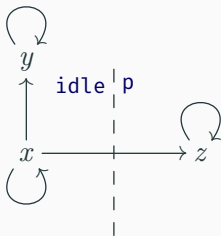
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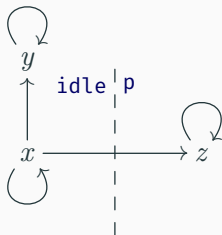
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- More about comparing expressive power in the next of slides

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- We also need to pre-compute extensions of all CTL subformulas used in  $C$

# Improvement

- make sure you do, e.g., backwards breadth-first search to avoid visiting same mode
- for  $[[E_C G \psi]]^M$ , you again start with **deleting** non- $\psi$  points ...
- ...find the maximal *strongly connected components (SCCs)* among those satisfying  $\psi$  ...  
**our old friend Tarjan's algorithm**
- and furthermore depending on  $C$  ...

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remember that a  $\psi$ -SCC represents a  $\psi$ -suffix rather than the entire path

*Added after the lecture:* Sorry for a typo in this clause

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- Of course, rather awkward syntax and semantics

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- Still more powerful: fixpoint calculi and parity games  
Beyond the scope of this lecture but amazingly effective